

Backface Detection

- It is a fast and simple object space method for identifying the backface of a polygon which is based on inside or outside test.

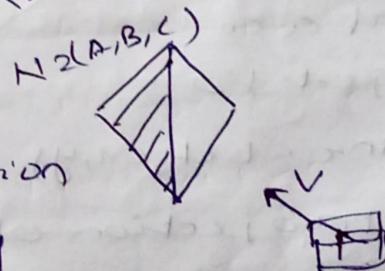
- A point $P(x, y)$ is inside a polygon surface with parameters A, B, C, D if

$$Ax + By + Cz + D < 0.$$

- when an inside point is along the line of sight to be a surface the polygon must be backface

- consider the normal vector N to a polygon surface which is cartesian component the polygon is backface

$$N \cdot V > 0.$$

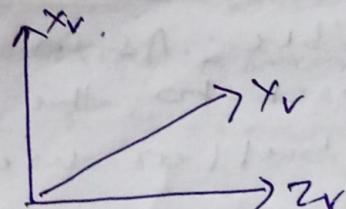
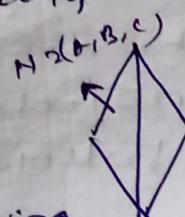


- If the object description have been converted

the projection co-ordinate our viewing dirn is parallel to the viewing axis Z_V axis then

$$V_2(0, 0, V_2) \text{ and}$$

$$V \cdot N = V_2 \cdot C$$



- In right hand viewing system the polygon is backface if $C < 0$.

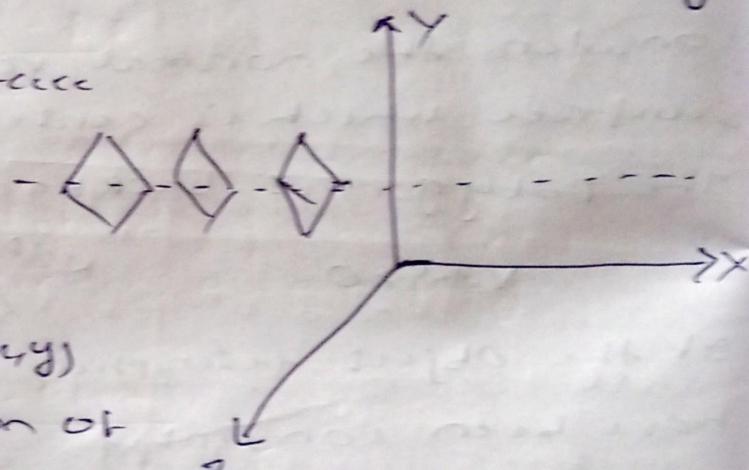
- In left hand viewing system the polygon is backface if $C > 0$.

* Visible surface detection or hidden surface elimination is the process of identifying which part of a scene are visible from a chosen viewing system.

Z-buffer/Depth-buffer method:

- It is an image space method for visible surface detection.
- Here the object depth is usually reduce from the view plane along z-axis of a viewing system
- s_1, s_2, s_3 are surfaces of an object.
- These surfaces are projected to view plane. Let (x, y) be the projection of (x_1, y_1, z) on the projection plane.
- So by measuring z-value of a point we can detect which surface should be visible. As in the diagram surface s_1 is closer to the projection plane.
- Z-buffer uses following two buffer

- i) Depth-buffer: store depth value for each (x, y) position as surface are processed.



RETRACT-BUFFER: store the intensity value
for the point (x, y) , where
 z -value is calculated.

then convert each polygon surface one
at a time.

calculate the depth at each (x, y) pixel position.
the calculated depth is compared to the
value of previously stored in the depth
buffer.

if the calculated depth is smaller than
the value stored in the depth buffer the
new depth value is stored and surface intensity
at that position is determined.

Algorithm:

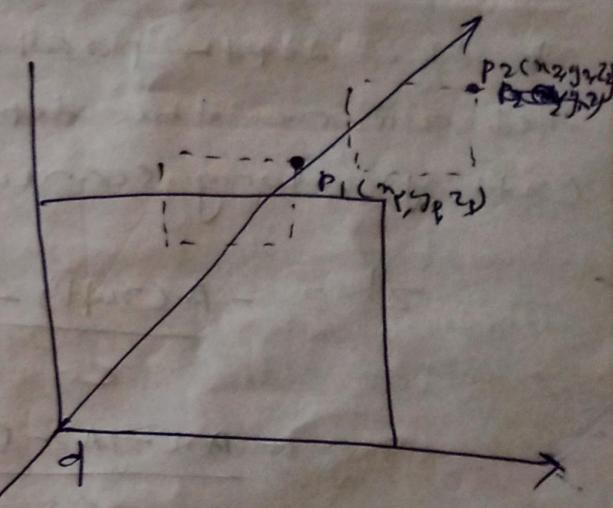
Initialize the depth
buffer and retract buffer
(that won all buffers
initialization (x, y))

depth(x, y) $\leftarrow 0$.

retract(x, y) \leftarrow background.

for each position on polygon surface
compare depth value to previously stored
depth value in depth buffer to determine
visibility

calculate the depth z for each (x, y) position
on the polygon.



II) If $z < \text{depth}(n, y)$ then set
 $\text{depth}(n, y) = z$

$\text{refresh}(n, y) = I_{\text{surface}}(n, y)$

$I_{\text{background}}$ = value of background intensity
 $I_{\text{surface}}(n, y)$ = projected intensity value
from the surface at pixel
position (n, y) .

calculation of Depth:

$$An + By + Cz + D = 0.$$

$$\Rightarrow z = -\frac{An + By + D}{C}$$

If the depth position (n, y) has been determined the depth z' of the next position $(n+1, y)$ along scanline is obtained by

$$z' = -\frac{A(n+1) + By + D}{C}$$

$$= -\frac{An + A + By + D}{C}$$

$$= -\frac{An + By + D}{C} - \frac{A}{C} \Rightarrow z - \frac{A}{C} = ③$$

$$x' = x - \frac{1}{m}$$

$$y' = y - 1$$

$$\Rightarrow z' = -\frac{A(x - \frac{1}{m}) + B(y - 1) + D}{C}$$

$$\Rightarrow z_1 = \frac{an + By - D}{c} + \frac{Am + B}{c}$$

$$\Rightarrow z_1 = z + \frac{Am + B}{c}$$

$$\Rightarrow \boxed{z_1 = z + B/c}$$

Illumination model: It is also known as shading model or lighting model.

- It's used to calculate the intensity of light that is reflected at a given point on surface
- There are three factors on which light effect depend on

i) Light source:

Light source is the light emitting source. There are 3 types light source

point source: if a point source emit a wave direction, it will form a very parallel wave front emitted by each point source which have been on the surface (con)

distributed source: Ray originate from a large area. The position, electromagnetic spectrum and shape determine the lighting effect.

2) surface: when the light fall on a surface part of it is absorbed. Now the structure decides the amount of reflection and absorption of light.

The position of the surface and position of an nearby surface also determining the light source - lighting effect.

3) observer: the observer position and sensor spectrum sensitivities also effect the lighting effect.

1. Ambient Illumination

Assume you are standing on a roof facing a building with glass exterior and sun rays are falling on that building reflected back from it and the falling on the object under observation this would be Ambient Illumination. In this case where source of light is considered

2. Diffuse Reflection:

It occurs on the surface which are rough and grainy. In this reflection the brightness of a point depend upon the angle made by the light source and the surface.

The reflected intensity I_{diff} of a point on the surface is

$$I_{diff} = k_d I_p \cos(\alpha) + k_s I_p (N \cdot L)$$

where I_p : the point light intensity

k_d : the surface diffuse reflectivity value of k_d varies from 0 to 1.

N : Surface normal

L : Light dir.

3) Specular Reflection:

When light falls on any shiny or glossy surface most of it is reflected back such reflection is known as specular reflection.

Color model:

A color model is an orderly system for creating a whole range of colors from a small set of primary colors.

There are two types color models

i) Subtractive

ii) Additive

i) Subtractive: This model was printing color. Color perceived in this model is reflected light.

ii) Additive: This model uses light to display colors color perceived in additive model as the result of transmitting light.

Bonus There are four color models on your syllabus i.e XYZ, RGB, YIQ and CMY. Out of this four two are very very important i.e RGB and CMY.

RGB: It is a additive color model for computer displays uses light to display color, color result from transmitting light.

→ Red + Green + Blue → white

CMY: It is a subtractive color model.

→ It is the standard color model used in offset printing for full color documents because such printing uses three of these three basic colors. It is often called three color printing.

→ Cyan + Magenta + Yellow → Black

YIQ: It is used in U.S commercial color television broadcasting (NTSC). It's a rotation of the RGB color space such that the Y-axis contains the luminance information allowing backwards compatibility with black-and-white colour TV, which display only one of the colour space.

XYZ: X, Y and Z are extrapolation of RGB created mathematically to avoid negative numbers. In 1931 there weren't any computers and are called tristimulus values. Y means luminance, Z is somewhat equal to blue and X is a mix of cone response curve chosen to be orthogonal to luminance and non-negative.